# **Unsupervised Classification**

Introduction to Clustering

Data Analysis – juliette.chevallier@insa-toulouse.fr INSA Toulouse, Applied Mathematics, 4th year

1. What is clustering? Why is it used? Principle and First Examples

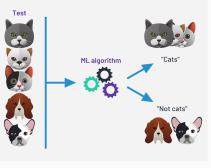
2. How to evaluate it? Tools to Evaluate and Compare Clusters

- 2.1 Intrinsic Quality of a Partition
- 2.2 Comparison Between two Partitions
- 3. How to choose a clustering algorithm? Course Outline

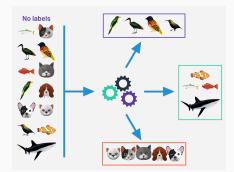
What is clustering? Why is it used? *Principle and First Examples* 

## Supervised vs. Unsupervised Classification

# Cluster Analysis From Wikipedia, the free encyclopedia Cluster analysis or clustering is the task of grouping a set of objects in such a way that objects in the same group (called a cluster) are more similar (in some sense) to each other than to those in other groups (clusters).



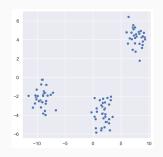
Supervised classification



 ${\sf Images from www.g2.com/articles/supervised-vs-unsupervised-learning}$ 

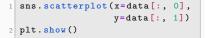
#### Unsupervised classification

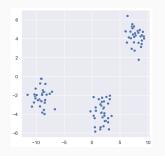
#### Toy Dataset – Python notebook available on Moodle



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## Some Applications in Real Life

Recommendation systems



• Image segmentation: Tumor identification, Ecological studies, etc.





See www.kdnuggets.com/2019/08/introduction-image-segmentation-k-means-clustering.html

• Unsupervised robotic sorting: Garbage-sorting bot, etc.

See The Everyday Robot Project from Alphabet

- Data-driven discovery of new chemicals
- Unsupervised image/signal classification



#### Principle of Clustering

We observe n individuals described by p variables:  $x_i = (x_{i1}, x_{i2}, \dots, x_{ip}) \in \mathcal{X}$ 

 $X = \begin{pmatrix} x_{11} & x_{12} & \dots & x_{1p} \\ x_{21} & x_{22} & \dots & x_{2p} \\ \vdots & \vdots & \ddots & \vdots \\ x_{n2} & x_{n2} & \dots & x_{np} \end{pmatrix}$ • Initial measurements
• Transformed measurements
• Coordinates after dimension reduction

 $\mathcal{X} = \mathbb{R}^p$ ,  $\{0,1\}^p$ ,  $[-\pi,\pi]^p$ ,  $\mathbb{R}^q \times \{0,1\}^{p-q}$ ,...

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**Classification:** Partitioning a collection of *heterogeneous* individuals into a set of *homogeneous* classes.

**Unsupervised:** No *a priori* partition of the n individuals, Number of classes K unknown. Set of data points on which we do not know the labels, but that we want to group together in a smart way.

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 $\implies$  Determine K classes  $\mathcal{P}_K = \{\mathcal{C}_1, \dots, \mathcal{C}_K\}$  of the *n* individuals from X such that a **class** is a collection of individuals:

- similar to each other, and
- dissimilar to the individuals of the other classes (well separated classes).

#### Inertia (for Quantitative Data)

- Assume quantitative variables and d<sub>q</sub> the Minkowski distance, i.e. the distance associated to the norm ||·||<sub>q</sub>.
- Let a partition  $\mathcal{P}_K = \{\mathcal{C}_1, \dots, \mathcal{C}_K\}$  into K classes.

Total inertia Total variance

$$I_{Tot} = \sum_{i=1}^{n} d(\mu, x_i)^q$$

Let 
$$\mu = rac{1}{n} \sum_{i=1}^n x_i$$
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center of gravity of the *point cloud*.

Interclass inertia Variance of class centers

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Intraclass inertia Variance of points in the same class

$$I_{Intra} = \sum_{k=1}^{K} \sum_{i \in \mathcal{C}_k} d(\mu_k, x_i)^q$$

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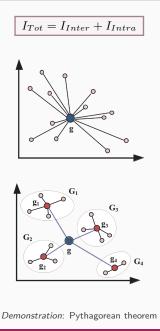
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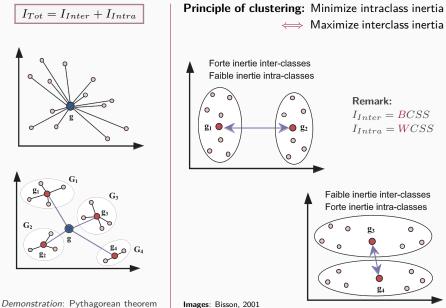
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## Huygens' Principle



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## Impossibility of an Exhaustive Search

**Disclaimer**: Here, we only deal with "hard classification" methods: an individual belongs to only one class, *i.e.* 

```
\forall i \in [\![1,n]\!], \quad \exists !k \in [\![1,K]\!] \text{ such that } i \in \mathcal{C}_k.
```

*Stirling numbers of the second kind*: Number of ways to partition a set of n elements into K nonempty subsets

$$S(n,K) = {n \\ K} = \frac{1}{K!} \sum_{j=0}^{K} (-1)^{K-j} j^n {K \choose j}.$$

 $\rightarrow S(100,3) \simeq 10^{47}$  partitions of n = 100 individuals into K = 3 classes,  $\rightarrow S(100,5) \simeq 10^{68}$  partitions of n = 100 individuals into K = 5 classes.

→ Impossibility of an Exhaustive Search.

## Quantify the Dissimilarity

• Clustering methods requires to be able to quantify the dissimilarity between observations.

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- Quantitative data: Minkowski distance, Euclidean distance, Mahalanobis, etc.
- Qualitative data: Rogers and Tanimoto dissimilarity, simple dissimilarity, *etc. Example*: Let x, y categorical with p features.  $d(x,y) = \sum_{j=1}^{p} \mathbb{1}_{\{x_j \neq y_j\}}$
- Mixed data: Gower metric, etc.

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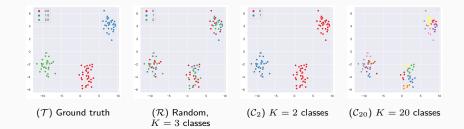
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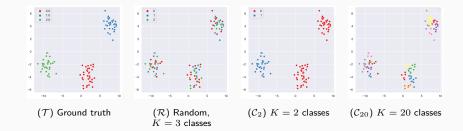
• Dimension curse: Beware of the behavior of distances in large dimensions!

How to evaluate it? Tools to Evaluate and Compare Clusters

## How to Evaluate Clustering Results?



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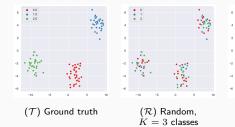


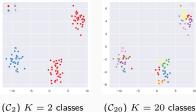
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#### **External metrics:**

Specific clustering metrics when ground truth is known.

#### How to Evaluate Clustering Results?





**Internal metrics:** *Real situation* No need to know the ground truth.

- Silhouette coefficient,
- Davies–Bouldin index,
- Dunn Index,
- *R*-Square (*RSQ*) and Semi-Partial R-Square (*SPRSQ*) criteria,
- Calinski-Harabasz score.

#### **External metrics:**

Specific clustering metrics when ground truth is known.

- Purity,
- Clustering accuracy,
- Folkes-Mallows index,
- Normalized Mutual Information.

#### Example of Internal Metric: Silhouette Coefficient

Let  $x_i$ , where  $i \in C_k$ . n points, K clusters.

• Cohesion: Mean distance between  $x_i$  and other points in  $C_k$ :

$$a(i) = \frac{1}{|\mathcal{C}_k| - 1} \sum_{j \in \mathcal{C}_k, j \neq i} d(x_i, x_j)$$

• **Separation**: Mean distance between  $x_i$  and the points of the closest other clusters:

$$b(i) = \min_{\ell \neq k} \frac{1}{|\mathcal{C}_{\ell}|} \sum_{j \in \mathcal{C}_{\ell}} d(x_i, x_j)$$

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→ Silhouette score:

• Point 
$$x_i: s(i) \in [-1, 1]$$

$$s(i) = \frac{b(i) - a(i)}{\max(a(i), b(i))}$$

#### Entire dataset:

$$S = \frac{1}{n} \sum_{i=1}^{n} s(i)$$
$$= \frac{1}{K} \sum_{k=1}^{K} \frac{1}{|\mathcal{C}_k|} \sum_{i \in \mathcal{C}_k} s(i)$$

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	$ $ ( $\mathcal{T}$ )	$(\mathcal{R})$	$(\mathcal{C}_2)$	$(\mathcal{C}_{20})$
Silhouette	0.83	-0.03	0.66	0.39

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#### Entire dataset:

$$\begin{split} S \ &= \frac{1}{n} \sum_{i=1}^n s(i) \\ &= \frac{1}{K} \sum_{k=1}^K \frac{1}{|\mathcal{C}_k|} \sum_{i \in \mathcal{C}_k} s(i) \end{split}$$

Function silhouette\_score from the sklearn.metrics package.

#### Inertia-Based Criteria

Let a partition  $\mathcal{P}_K$ .

• **R-Square**: 
$$RSQ(\mathcal{P}_K) = \frac{I_{Inter}(\mathcal{P}_K)}{I_{Tot}} = 1 - \frac{I_{Intra}(\mathcal{P}_K)}{I_{Tot}}$$

• Semi-Partial R-Square:  $SPRSQ(\mathcal{P}_K) = \frac{I_{Inter}(\mathcal{P}_K) - I_{Inter}(\mathcal{P}_{K-1})}{I_{Tot}}$ 

• Calinski-Harabasz (CH):  $PseudoF(\mathcal{P}_K) = \frac{I_{Inter}(\mathcal{P}_K)}{I_{Intra}(\mathcal{P}_K)} \times \frac{n-K}{K-1}$ 

	$(\mathcal{T})$	$(\mathcal{R})$	$(\mathcal{C}_2)$	$(\mathcal{C}_{20})$
Silhouette	0.83	-0.03	0.66	0.39
Calinski-Harabasz	1549.85	0.03	225.78	1009.70
Davies-Bouldin	0.24	64.40	0.45	0.66

## **Example of External Metric: Purity**

Let  $\mathcal{P}^{\star}_L = \{\mathcal{C}^{\star}_1, \dots, \mathcal{C}^{\star}_{K^{\star}}\}$  be the ground truth partition, n points.

Consider a partition  $\mathcal{P}_K = \{\mathcal{C}_1, \ldots, \mathcal{C}_K\}.$ 

$$\mathcal{P}urity(\mathcal{P}_K) = \frac{1}{n} \sum_{k=1}^{K} \max_{\ell \in [\![1,K^\star]\!]} |\mathcal{C}_{\ell}^{\star} \cap \mathcal{C}_k|$$

	$(\mathcal{T})$	$(\mathcal{R})$	$(\mathcal{C}_2)$	$(\mathcal{C}_{20})$
Silhouette	0.83	-0.03	0.66	0.39
Calinski-Harabasz	1549.85	0.03	225.78	1009.70
Davies-Bouldin	0.24	64.40	0.45	0.66
Purity score	1	0.36	0.67	1

Issue: More clusters, better score.

How to evaluate it? Tools to Evaluate and Compare Clusters

#### How to Compare two Clusterings?

Let us suppose that we have obtained two partitions from the same data :

$$\mathcal{P}_K = \{\mathcal{C}_1, \dots, \mathcal{C}_K\}$$
 and  $\mathcal{Q}_L = \{\mathcal{D}_1, \dots, \mathcal{D}_L\}$ 

Question: How to compare these two classifications?

• Contingency table,

. . .

- Rand Index (RI) and Adjusted Rand Index (ARI),
- Variation of information,



# (Adjusted) Rand Index

$\mathcal{P}_K$ vs. $\mathcal{Q}_L$	Grouped in $\mathcal{P}_K$	Separated in $\mathcal{Q}_L$	
Grouped in $\mathcal{P}_K$	а	b	$egin{array}{llllllllllllllllllllllllllllllllllll$
Separated in $\mathcal{Q}_L$	С	d	c + d: Disagreements.

• **Rand Index**: Proportion of point pairs that are grouped in the same way in both partitions.

$RI(\mathcal{P}_{K}, \mathcal{Q}_{L}) =$	a + d
$ \mathbf{n}(\mathbf{P}_K, \mathbf{Q}_L) -  $	$\overline{a+b+c+d}$

# (Adjusted) Rand Index

6

$\mathcal{P}_K$ vs. $\mathcal{Q}_L$	Grouped in $\mathcal{P}_K$	Separated in $\mathcal{Q}_L$	
Grouped in $\mathcal{P}_K$		b	$a+b$ : Agreements between $\mathcal{P}_K$ and $\mathcal{Q}_L.$
Separated in $\mathcal{Q}_L$	С	d	c+d: Disagreements.

• Rand Index: Proportion of point pairs that are grouped in the same way in both partitions.

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• Adjusted Rand Index: Let 
$$n_{k\ell} = |\mathcal{C}_k \cap \mathcal{D}_\ell|$$
,  $n_{k+} = \sum_{\ell=1}^L n_{k\ell}$ ,  $n_{+\ell} = \sum_{k=1}^K n_{k\ell}$ .

• 
$$RI = \sum_{k\ell} {\binom{n_{k\ell}}{2}}$$
  
•  $\mathbb{E}[RI] = \frac{\sum_k {\binom{n_{k+}}{2}} \times \sum_\ell {\binom{n_{+\ell}}{2}}}{{\binom{n}{2}}},$ 

Indices obtained by randomly partitioning the data

• 
$$\max(RI) = \frac{1}{2} \left( \sum_{k} \binom{n_{k+}}{2} + \sum_{\ell} \binom{n_{+\ell}}{2} \right)$$

$$\boldsymbol{ARI}(\mathcal{P}_{K}, \mathcal{Q}_{L}) = \frac{RI - \mathbb{E}[RI]}{\max(RI) - \mathbb{E}[RI]}$$

The closer the ARI is to 1, the more similar the two partitions are.

## **Contingency Table**

• Contingency table to observe if classes are shared, split, etc.

$n_{k\ell} =  \mathcal{C}_k \cap \mathcal{D}_\ell $	$\mathcal{P}_K$ vs. $\mathcal{Q}_L$	$\mathcal{D}_1$	$\mathcal{D}_2$		$\mathcal{D}_L$	Sums
$= \# \left\{ i \in \llbracket 1, n \rrbracket \mid i \in \mathcal{C}_k \cap \mathcal{D}_\ell \right\}$	${\mathcal C}_1$	$n_{11}$	$n_{12}$		$n_{1L}$	$n_{1+}$
	$\mathcal{C}_2$	$n_{21}$	$n_{22}$		$n_{2L}$	$n_{2+}$
$n_{k+} = \sum_{\ell=1}^{l} n_{k\ell}$	:	÷	÷	·.	÷	÷
$\ell = 1$ $K$	$\mathcal{C}_K$	$n_{K1}$	$n_{K2}$		$n_{KL}$	$n_{K+}$
$n_{+\ell} = \sum_{k=1} n_{k\ell}$	Sums	$n_{+1}$	$n_{+2}$		$n_{+L}$	n
		30 39 30 40 8 8	For the second sec	22 23 20 20 20 20 20 20 20 20 20 20 20 20 20		
$(\mathcal{T})$ vs. $(\mathcal{R})$	$(\mathcal{T})$ vs. $(\mathcal{C}_2)$		$(\mathcal{R})$	vs. ( $\mathcal{C}_2$	2)	

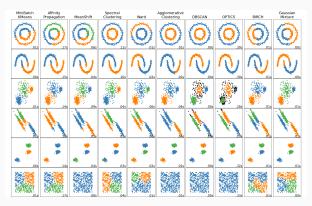
Functions confusion matrix and ConfusionMatrixDisplay from sklearn.metrics.

# How to choose a clustering algorithm? *Course Outline*

## A Variety of Methods

- Clustering methods distinguish by:
  - Type of "similarity" between individuals: Distance, probability distribution, shape, etc.
  - Type of "partitioning": Hard or fuzzy clustering.

- Various categories of methods:
  - Distance-based,
  - Connectivity-based,
  - Density-based,
  - etc.

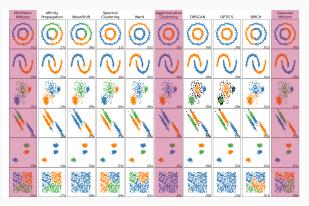


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# **Different Families of Clustering Algorithms**

	Distance-based	Connectivity-based	Density-based
Pros	<ul> <li>Can conduct inference on new data points</li> <li>Usually fast</li> </ul>	<ul> <li>Does not need access to data points values (only distances)</li> <li>Can handle non linearly separated clusters</li> </ul>	<ul> <li>Does not need access to data points values</li> <li>Can handle non linearly separable clusters</li> <li>Does not need number of clusters</li> <li>Can handle outliers</li> </ul>
Cons	<ul> <li>Number of clusters required</li> <li>No outlier detection</li> <li>Need access to point values</li> </ul>	<ul> <li>Number of clusters required</li> <li>No outlier detection</li> <li>Usually slow</li> <li>Cannot conduct inference</li> </ul>	<ul> <li>Usually slow</li> <li>Cannot be used for inference</li> </ul>
Example	K-means	Hierarchical clustering	DBSCAN